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Alzarok, Hamza, Fletcher, Simon, Longstaff, Andrew P. and Myers, Alan

Assessment of the positioning accuracy of a small articulated robot during machining operations

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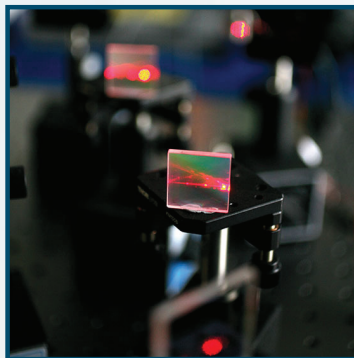
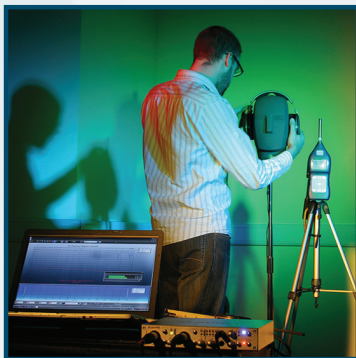


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