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## STANDARD DRIVE CYCLE RECREATION FROM GENERAL DRIVING BEHAVIOUR

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### ABSTRACT

In many parts of the world car manufacturers are required by law to state the fuel economy performance of their vehicles when undertaking one or more Standard Drive Cycles such as the Urban and Extra Urban test cycle definitions required in Western Europe. Such Standard Drive Cycles have their roots in obscure vehicle testing undertaken decades ago in the USA, and no physical test track exists in Europe which enables the precise re-creation of these test characteristics. Furthermore, the fundamental validity of these test cycles as a means of gauging and comparing passenger car fuel economy is seldom considered. This paper documents the early stages of a research project which aims to segment the Standard Drive Cycle definitions into a series of operating characteristic windows which can then be searched for and automatically extracted from general driving behaviour of a car on the road, and thereafter concatenated to re-creating a real-world equivalent of the Standard Drive Cycle without the need for rolling road or laboratory testing.

**Keywords:** Drive Cycle, Fuel Economy.

### INTRODUCTION

Fuel economy has risen to prominence in recent years and most automobile markets require adherence to local fuel economy standards. It has been realised that fuel economy figures importantly to reduce carbon dioxide emissions and to deal with energy conservation. Globally, the need for oil has been on the increase even though there is a global economic recession (An *et al.*, 2011, p.1).

The measurement of fuel economy takes on various different forms but the basic contention is to see what unit volume of fuel is required to travel a certain distance (GFEI, 2013). There is however no touchstone fuel economy standard in use around the world and the large automobile markets each have their internal standards (An *et al.*, 2011, p.4). Current fuel economy measurement systems rely on localised standard drive cycles that differ from each other in design leading to a lack of consensus. In addition, the various drive cycles in use around the world have fundamental validity concerns that further diminish their credibility.

This paper will look into early attempts to create a standardised drive cycle for fuel economy measurement that relies on operating characteristics from automobiles on the road. This approach stands in contrast to the rolling road or laboratory testing approaches used by various drive cycles.

### CURRENTLY IMPLEMENTED DRIVE CYCLES

Various regions around the world have their own drive cycles in use for fuel economy testing. The differing drive cycles can be listed as shown in the table 1.

The table 1 indicates that most standard drive cycles in use arrive from American, Japanese or European standard drive cycles. Local regulations dictate how standard driving cycles are formulated (Pundir, 2008, p.13) but it must be kept in mind that fuel economy tends to vary widely depending on the operating conditions which in turn requires replicable test procedures (Faiz *et al.*, 1996). It is notable that most standard drive cycles tend to represent driving conditions in urban environments, on highways or through a combination of both.

It is typical to see driving cycles varying between each other based on the tested parameters. Differing legislation and legal requirements tend to produce standard driving cycles that produce different results for the same automobile being tested. A comparison of the tested parameters for driving cycles in the United States, European Union and Japan are shown in Table 2 to highlight varying requirements and hence varying results from differing standard driving cycles (Pundir, 2008, p.15).

Table 1 - Fuel economy and GHG emission standards for vehicles around the world sourced from (An *et al.*, 2011, p.4)

Region	Type	Measure	Structure	Test Method
United States	Fuel	mpg	Footprint-based value curve	US CAFÉ
California	GHG	g/mile	Car/LDT1	US CAFÉ
European Union	CO <sub>2</sub>	g/km	Weight-based limit value curve	EU NEDC
Japan	Fuel	km/L	Weight-bin based	Japan 10-15 JC08
China	Fuel	L/100-km	Weight-bin based	EU NEDC
Canada	Fuel	L/100-km	Cars and light trucks	US CAFÉ
Australia	Fuel	L/100-km	Overall light-duty fleet	EU NEDC
South Korea	Fuel	km/L	Engine Size	US CAFÉ

Table 2 - Comparisons of the European Union, the United States and Japanese test cycles sourced from (Pundir, 2008, p.15)

Test cycle	Duration (s)	Length (km)	Average speed (km/h)	Maximum speed (km/h)	Maximum acceleration (m/s <sup>2</sup> )	% idle time
NEDC	1180	11.01		120	0.833	23.4
EPA Highway	765	16.45	77.4	96.4	1.475	0
EPA City	1371	17.85	31.7	91.3	1.475	17.4
Japan 10-15	660	4.16	22.7	73.5		31.4
JC08	1204		24.5	81.6	1.7	

The presence of differing testing methods through parameter variation means that certain standard drive cycles are more stringent than others. Estimates place the New European Driving Cycle (NEDC) at 12% more stringent than Corporate Average Fuel Economy (CAFE). Comparatively, Japanese testing cycles are some 30% more stringent than CAFE and 15% more stringent than NEDC (Pundir, 2008, p.16).

### USES FOR STANDARD DRIVE CYCLES

Standard drive cycles serve a number of important purposes. Other than fuel economy reporting, standard drive cycles allow measurement of emissions levels. The increasing contribution of vehicular smoke to global emissions (Kamble *et al.*, 2009, pp.132-40) makes them a larger contributor to air pollution and global warming (Al Zaidi, 2013, p.13). In addition, standard drive cycles allow an appraisal of vehicle performance (Mi *et al.*, 2011, pp.30-31).

### PROBLEMS WITH STANDARD DRIVE CYCLES

Standard drive cycles in use tend to display differentiated behaviour from real world driving conditions. Consequently, measurements from standard drive cycles and real world automobile use is significantly different. Research estimates that this discrepancy has increased from 8% in 2001 to some 21% in 2012 given the exploitation of loopholes in testing systems and the provision of air conditioning as a standard vehicle accessory (Mock *et al.*, 2012, pp.1-3).

There is evidence to indicate that vehicle manufacturers manipulate standard driving cycles in order to favour production options. Emissions are optimised for previously known speeds, acceleration, gear shifts etc. to suit engine operating characteristics. When vehicles approved by standard driving

cycles are tested in the real world, the emissions results and other results are markedly different from test cycle results. For instance, research indicates that the emission of nitrous oxides in real world driving conditions from diesel automobiles are significantly higher than those derived from NEDC drive cycle tests. Research also indicates that nitrous oxide emissions have not shown any major reductions in the last decade or so (T&E Bulletin, 2006, p.1).

## METHODS

A number of different driving cycles have been developed some of which have become standard. However, the current research focuses on the four major standardised driving cycles based on regional categorisation since these cycles are used wherever standard cycles do not exist (Tong *et al.*, 1999) (Tamsanya *et al.*, 2006). Comparisons of major standardised driving cycles led to the conclusion that NEDC be utilised in order to carry out further research. The European Union has already come to agreement with car manufacturers to reduce carbon dioxide emissions given changing lifestyles, need for greater mobility and an inclination for personal transport.

## CHOSEN VEHICLE AND SETTINGS

A Nissan Patrol has been chosen for testing in urban as well as extra urban drive settings. The contention is to research the greenhouse gas emission levels of Nissan Patrol in the aforementioned drive settings.

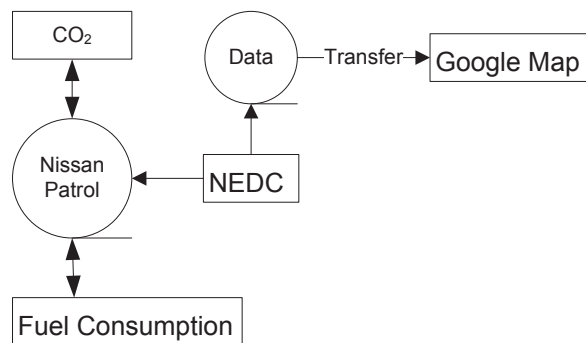


Figure 1 - Theoretical Framework

The Nissan Patrol has been selected as the vehicle of choice for testing since it provides established fuel economy levels and is seen as a green vehicle. In addition, the engine and drive train are simple to modify so as to add new equipment for on road testing and data collection. Also, the selected vehicle is a jeep and can be utilized for off road testing at a later phase.

Operation of the Nissan Patrol would allow data collection regarding fuel consumption and carbon dioxide emissions. The Nissan Patrol would be tested according to the NEDC framework as per guidelines described later. Data collected through NEDC testing for fuel consumption and carbon dioxide emissions would be routed to Google Maps. This would allow real time tracking of fuel consumption and carbon dioxide emissions.

Using the NEDC framework, the fuel consumption and carbon dioxide emission levels of a Nissan Patrol will be tabulated. Information gathered here would be utilized to:

- Comparing differences between the urban and extra urban driving cycle;
- Using simulated data as a benchmark for comparison with on road testing;
- Development of pathways that allow data gathering during on road vehicle travel.

## PHASE ONE: SIMULATION

A Partnership for a New Generation of Vehicles (PNGV) System Analysis Toolkit (PSAT) will be used for system wide model validation. This will allow the determination of fuel consumption, carbon dioxide emissions levels and vehicular performance (Pasquier *et al.*, 2013).

A total of two gas sensors have been used for data collection regarding gas temperature. A single gas sensor could have been used but failure of the gas sensor would have led to data loss. To avoid such a situation, an extra gas sensor has been installed as a redundant failure control. Under regular

operation, data collected from both gas sensors would allow confirmation of collected values. In addition, data collected from both gas sensors would be averaged for use.

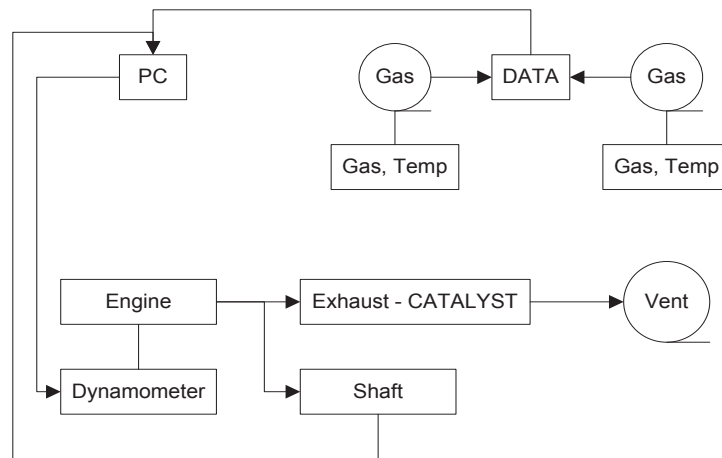


Figure 2 - The schematic diagram of Phase One

The engine of the Nissan Patrol was tested to discern its operating characteristics. For testing, the engine was coupled to a McClure 215 kW transient dynamometer. The testing arrangement was controlled by utilizing a CP Cadet V14 control system. Additionally, the exhaust was changed to house the catalyst being utilized. The power train was simulated using PSAT-PRO software and validation was performed for components requiring control.

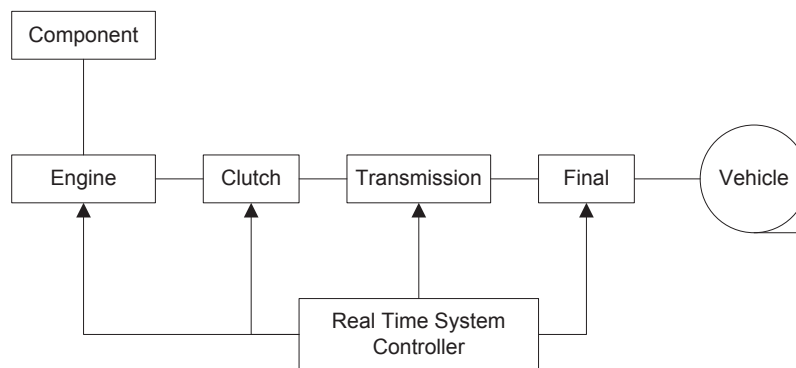


Figure 3 - Schematic Diagram of Powertrain adopted from (Pasquier *et al.*, 2013)

## PHASE TWO: EXPERIMENTATION

Experimentation will be carried out through the chase car method given its credibility. The researcher will follow the vehicle under observation using another vehicle and observe the driving behaviour. In addition, the researcher would be able to utilise laser instruments to record real time data regarding relative distance between both vehicles. In turn, this allows the researcher to record speed and acceleration of the selected vehicle. The data collection would be carried out on board the Nissan Patrol while the researcher follows and factors in issues that the selected vehicle's driver would not be considering. The car chase method also allows the researcher to factor in driver behaviour that is an often neglected part of similar research.

To ensure steady driver behaviour during testing, a professional driver will be enlisted through outdoor clubs and Nissan dealerships. The identity of the driver will be kept secret in order to preserve the privacy of the concerned individual. It may be argued that the chase car method only works if the driver is not aware that he is being studied. However, it is felt that it will be fitting to take a qualitative approach because the vehicle for study is already identified and since the driving settings (urban and extra urban) are already identified. It has been agreed that using these parameters it would be suitable to inform the participants of the research on issues that pertain to them only.

### PHASE THREE: SOFTWARE

A software program will be developed in order to provide live information regarding greenhouse gas emission levels from the studied vehicle. Currently two software systems for greenhouse gas emission monitoring are under consideration namely COPERT 4 and MOVES. Each software allows Controller Area Network (CAN) integration to facilitate communication between various automotive systems.

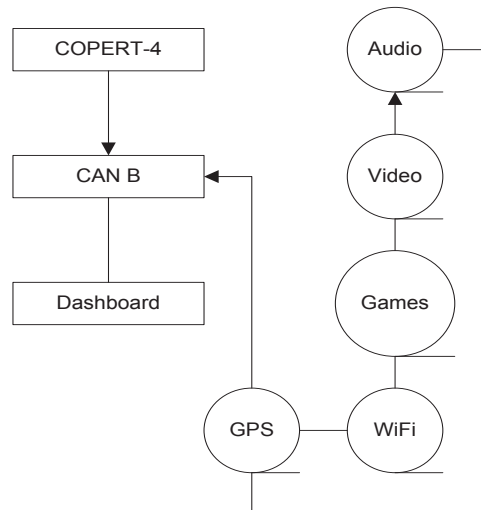


Figure 4 - The Schematic Diagram of CAN

CAN implementation allows collection of required information such as greenhouse gas emission levels. Information generated in this manner can either be stored or uploaded to online resources such as Google Maps. This in turn allows live real time feed of collected data.

### CONCLUSION

Standard drive cycles are available for fuel consumption checks, emission level testing and vehicle performance measurement. However, the accuracy of such testing mechanisms and biases inculcated by automobile manufacturers has discounted the credibility of such systems. This research aims to utilise a Nissan Patrol to implement urban and extra urban NEDC driving settings to fathom greenhouse gas emission and vehicle performance in real world driving conditions. The project will pass through software simulation, on road tests and finally software implementation to discover how NEDC's studied drive settings tend to differ from real world conditions.

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