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Feasibility Study of a Take-Home Array-Based Functional Electrical Stimulation System With Automated Setup for Current Functional Electrical Stimulation Users With Foot-Drop

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1 **Objective:** To investigate the feasibility of unsupervised community use of an array-based
2 automated setup (AS) functional electrical stimulator (FES) for current foot-drop FES users.

3 **Design:** A feasibility study.

4 **Setting:** Participants' gait, total setup (TS) times and satisfaction were evaluated twice in the
5 gait laboratory. Usage, AS times and problems encountered were recorded during a two
6 week period of unsupervised use.

7 **Participants:** Participants (N=7) with diagnosis of uni-lateral foot-drop of central
8 neurological origin (>6mo), who were regular users of a foot-drop FES system (>3mo).

9 **Intervention:** Array-based AS FES system for foot-drop (ShefStim).

10 **Main Outcome Measures:** Logged usage; TS times for both FES systems and logged AS times
11 for ShefStim; diary recording of problems experienced; Quebec User Evaluation of
12 Satisfaction with assistive Technology (QUEST 2.0) questionnaire; walking speed; ankle
13 angles at initial contact and foot clearance during swing.

14 **Results:** All participants were able to use ShefStim. TS took longer with ShefStim than
15 participants' own FES systems and AS was longer than in a previous study of a similar system
16 (1). Some problems were experienced but overall participants were as satisfied with
17 ShefStim as their own FES systems. The increase in walking speed (N=7), relative to no
18 stimulation, was comparable between both systems and appropriate ankle angles at initial
19 contact (N=7) and foot clearance during swing (N=5) were greater with ShefStim.

20 **Conclusions:** This study demonstrates, for the first time, that an array-based AS FES system
21 (ShefStim) for foot-drop can be successfully used unsupervised. Despite setup taking longer
22 and some problems users are satisfied with it and it would appear as effective, if not better,
23 at addressing the foot-drop impairment. Further product development of this unique
24 system, followed by a larger-scale and longer-term study is required before firm conclusions
25 about its efficacy can be reached.

26 *Word count: 290*

27 **Key words:** electric stimulation therapy; peroneal nerve; hemiplegia; gait disorders,
28 neurologic; rehabilitation

29 **Abbreviations:**

30 Functional electrical stimulation=FES; Automated setup=AS; Odstock drop foot
31 stimulator=ODFS; Inter-quartile range=IQR; Standard deviation=SD; Total setup=TS; Quebec
32 User Evaluation of Satisfaction with assistive Technology=QUEST; Dorsiflexion=DF;
33 Plantarflexion=PF

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INTRODUCTION

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The efficacy, and safety, of functional electrical stimulation (FES) as a treatment for foot-drop of central neurological origin is well established (2), however, usability issues have been noted (3, 4). In fact a survey of new and established users of the Odstock drop foot stimulator found that 44% of users reported difficulties in locating the correct electrode position (4), and this finding is of particular relevance to this study. Traditional single-channel surface foot-drop FES systems deliver current via a pair of electrodes, accurate placement of which is crucial to the correct functioning of the system. The optimal site for stimulation may vary from day-to-day and even throughout a day which further complicates the setup process (4). Interestingly, despite wide recognition of this issue (5), only one study specifically reported on the impact of user-defined electrode placement on functional outcomes (1), finding a poorer foot response when participants located electrodes themselves, compared with clinician setup.

In response to this issue, new designs of FES systems have been produced. These include electrodes integrated into cuffs (6, 7) and implantable systems (5, 8). Most recently, Heller *et al.* (1) reported on an array-based FES stimulator for foot-drop. The system uses the principle of a 'virtual electrode'. Stimulation is delivered via a 4x4 cluster of small electrodes, chosen from within an 8x8 array. The choice of which virtual electrode to use and at what level to stimulate is determined automatically during setup by an algorithm, which uses as its input the foot response to stimulation. This approach fully automates the setup process (both location and amplitude of stimulation) thus, potentially, reducing setup difficulty. Heller's study found that automated setup (AS) was comparably effective and quicker than user setup conventional FES. The system, originally studied by Heller, has been

59 further developed and CE marked as ShefStim. This paper is the first feasibility (9) study of
60 ShefStim which combined a period of unsupervised use in conjunction with gait evaluation
61 at the start and end of the study period. The primary aim was to investigate whether
62 ShefStim could be used, unsupervised, by foot-drop FES users within the community
63 environment. In addition a number of other sub-aims were addressed. These were to
64 investigate:

- 65 1. The community-usage patterns and user-satisfaction with ShefStim.
- 66 2. The total setup (TS) time compared with their own FES system, as well as AS times
67 for ShefStim.
- 68 3. The effects of ShefStim on walking speed, ankle angles (at initial contact) and foot
69 clearance during swing, compared with participants' own FES system.

70 *Word count: 404*

71 **METHODS**

72 **ShefStim system**

73 A detailed description of the operating principles of the stimulator, and changes in order to
74 achieve CE marking, are given in the Heller *et al.* paper (1). The same fixed parameters
75 (monophasic waveform, charge-balanced, 40Hz, 160 μ s) were used but the system used in
76 Heller's study restrained the leg in a support during the AS process. This was deemed
77 impractical for a take-home device so instead users were requested to extend their leg and
78 rest their heel on the floor during home AS.

79 **Figure 1:**

80 The ShefStim consists of (Fig. 1): a leg-worn stimulator (Fig. 1. a.) housed in a modified knee
81 sleeveⁱ (Fig. 1. b.); a flexible printed circuit board array of 64 electrodes (cathode electrodes)
82 (Fig. 1. c.), covered with a thin layer of high resistivity hydrogel (10-12) . Sweat ingress
83 changes the conductive properties of the hydrogel sheet so a replacement array fitted with
84 a new sheet of hydrogel is used each day (12); a conventional footswitchⁱⁱ; a conventional
85 anodeⁱⁱⁱ (Fig. 1.d.) and a foot sensor and remote control device housed in a bespoke foot-
86 pod^{iv} (Fig. 1. e.). The foot sensor and remote control device detects foot orientation,
87 provides voice commands during AS and acts as a handheld remote unit post AS, allowing
88 the user to pause, and change intensity as required.

89 *Word count: 209*

90 **Donning the system**

91 To don ShefStim the following steps are required:

- 92 1. The footswitch (Fig. 1. f.) is placed under the heel, with the connecting cable
93 extending from the shoe.
- 94 2. The knee sleeve is donned aligning the stimulator pocket with the long axis of the
95 tibia
- 96 3. The stimulator is placed in the knee sleeve's stimulator pocket
- 97 4. The foot-pod, containing the foot sensor and remote control device is positioned
98 over the shoe locating it approximately centrally over the dorsum of the foot and
99 attached with Velcro[®]

- 100 5. Electrode array placement: the centre of the third row of electrodes down from the
101 top of the array is aligned with the head of the fibula and the inner edge parallel to
102 the tibia.
- 103 6. The electrical connector for the array (Fig. 1. g.) is inserted into the array socket on
104 the side of the stimulator and the array is secured with a Velcro® strap.
- 105 7. The self-adhesive anode is positioned over the tibialis anterior.
- 106 8. The footswitch connector (Fig. 1. h.) is inserted in the stimulator.

107 AS is then started.

108 *Word count: 177*

109 **AS**

110 For a more detailed description of the AS algorithm refer to Heller's study (1). The only
111 difference between the algorithm used in Heller's study (1) and the ShefStim algorithm,
112 relates to the cost function used in stage 3 of the setup process. The cost function enables
113 many factors that are not directly comparable (e.g. the angle of dorsiflexion (DF) and the
114 stimulation current) to be combined into one optimisation routine. In this case, for example,
115 the angle of DF and the stimulation current are related and the benefits of increasing DF
116 have to be balanced against the potential disadvantages of increasing current excessively.
117 The cost function attributes each a cost score, the lower the cost the better, and the
118 optimisation routine is used to find a minimum cost solution. Compared with the cost
119 function described in Heller's study, the one used in ShefStim reduced the degree of
120 eversion associated with zero cost from 10 to 5 degrees. This change was implemented
121 following observation of excessive (>10 degrees) eversion in 19% of Heller's participants.

122 *Word Count: 171*

123 **Participants**

124 Ethical Approval was granted from the University of Salford (REP10/113) and the integrated
125 research application system (10/H1003/107) for ten participants. Existing foot-drop FES
126 users within the North-West region were given information by clinicians. Interested
127 participants contacted the chief investigator. Inclusion/exclusion criteria are shown in Table
128 1.

129 **Table 1:**

130 *Word count: 46*

131 **Protocol**

132 At visit 1 participants attended the University of Salford gait laboratory and were provided
133 with standard shoes^y for all conditions to avoid the potential impact of different footwear
134 on foot clearance (13). Participants walked approximately five metres along the gait
135 laboratory up to five times at a self-selected speed initially with no stimulation and then
136 with participant's own FES system (self-setup). Following visit 1 the knee sleeve, stimulator
137 and electrode arrays were prepared for that individual. Participants returned for visit 2
138 where fitting was completed, rising/falling ramps and extension configured, adjustments
139 made to AS settings if required (to ensure appropriate virtual electrode selection) and
140 ShefStim use taught. Following two weeks of unsupervised use of ShefStim at home (with a
141 home-visit after approximately one week to replenish arrays and answer any queries)
142 participants returned to the gait laboratory (visit 3) which duplicated visit 1 but using
143 ShefStim rather than their own FES system.

144 *Word count: 151*

145 **Measures**

146 **Estimate of usage** (between visits 2 and 3)

147 Usage data has been collected in previous foot-drop FES studies (14-18). ShefStim logs the
148 number of heel lifts per day which can be used as an estimate of usage.

149 *Word count: 29*

150 **TS** (visits 1 and 3) and **AS time** (between visits 2 and 3).

151 With one notable exception (1), setup time has been largely neglected in previous foot-drop
152 FES research . TS times, defined as time from first starting to don equipment to being
153 satisfied with the outcome and walking away (including AS time for ShefStim), were
154 recorded for participants' own FES (visit 1) and ShefStim (visit 3). Average AS time (time for
155 AS to complete) was logged by ShefStim.

156 *Word count: 65*

157 **Diary recording problems during community use** (between visits 2 and 3).

158 Problems encountered were recorded in a paper diary by each participant. User-reported
159 problems have been collected previously (15) but never during the period of use. Recorded
160 problems were collated and grouped into two categories (19): External and Setup. External
161 were classed as being independent of the stimulator design and so referred to the housing
162 of ShefStim (knee sleeve), issues with the standard wired footswitch or issues with charging.
163 Setup was defined as any problem related to setup or satisfaction with the foot response.

164 *Word count: 81*

165 **User-satisfaction** (visits 1 and 3)

166 User-satisfaction has previously been captured using purposive questionnaires (4, 15, 18).
167 Given the risk of bias and lack of validation we sought an alternative. The Quebec User
168 Evaluation of Satisfaction with Assistive Technology (QUEST 2.0) device scale (20) is a
169 validated user-satisfaction measure . Participants rated their satisfaction against eight single
170 item criteria (dimensions, weight, ease of adjustment, safety and security, durability, ease of
171 use, comfort, effectiveness) using a five-point Likert scale (1=not satisfied at all to 5= very
172 satisfied: maximum score=40) for their own FES system and ShefStim. In addition,
173 participants ranked their top three priorities from the eight criteria.

174 *Word count: 97*

175 **Speed and ankle angles at initial contact** (visits 1 and 3)

176 Increased walking speed indicates an improvement in overall walking performance (21) and
177 is frequently used in FES research (22, 23). Measuring walking speed over five metres from a
178 static starting position is a validated measure with neurological populations (24) and was
179 calculated by averaging the velocity of a recorded waist marker (L3 vertebra) over the
180 measurement space (13).

181 Foot-drop leads to abnormal joint alignment during stance (25) with a tendency for
182 plantarflexion (PF) and inversion (21) which can reduce ankle stability. Sagittal and frontal
183 plane ankle angles were captured at initial contact to measure this. The calibrated
184 anatomical system technique (CAST)(26, 27) was used for shank marker placement. Foot
185 marker placement was based on the shod-foot model by Pratt *et al.* (28).

186 Data for both speed and ankle angles was captured at 100Hz using a 16-camera 3D motion
187 analysis system^{vi}; a fourth-order low-pass Butterworth filter was used with a 6Hz cut-off
188 frequency. Ankle angles at initial contact were analysed using Visual 3D^{vii}

189 *Word count: 152*

190 **Foot clearance during swing** (visits 1 and 3)

191 Foot-drop is associated with an increased risk of tripping and falling due to a lack of foot
192 clearance during swing phase (29). Foot clearance was obtained for seven different points
193 on the shoe sole as described in Thies *et al* (13). Only three of the seven markers from Thies'
194 study (13) (distal toe, medial and lateral forefoot) were investigated since these were
195 deemed most relevant. Healthy gait consistently has a minimum clearance value during
196 swing (13, 30). Hemiplegic gait, however, has an altered clearance trajectory and does not
197 always produce a minimum value during swing, so an alternative and consistently definable
198 point along the trajectory was chosen. Specifically, in this study it was calculated at the
199 moment in time when the reference point on the shoe sole passed the contra-lateral medial
200 malleolus. Data was processed using Matlab^{viii} code (13).

201 *Word count: 133*

202 *Total methods word count: 1311 (not including sub-headings)*

203 **Data Analysis**

204 As a feasibility study (9, 31), statistical analysis was limited to graphical representation of
205 data and descriptive methods. Ratio data (AS log data, speed and ankle angles at initial
206 contact) was analysed using mean and standard deviation (SD). Median was used for

207 skewed data (usage, TS times and toe clearance (32) , with inter-quartile range(IQR)) and
208 ordinal data (QUEST (33)).

209 *Word count: 56*

210 **RESULTS**

211 **Table 2:**

212 Table 2 provides participant characteristics. Prior to data collection three participants were
213 withdrawn (1, 6, 10). The withdrawal of participants 1 and 10 was due to unrelated medical
214 issues. Subject 6 was withdrawn as it became clear, post recruitment, that he was not a
215 regular user of FES for foot-drop. He had discontinued use following ankle instability
216 problems and a number of falls. The average age of the remaining participants was 58 yrs.
217 (SD 12.9) which is comparable to other foot-drop FES studies (1, 21, 34). Of the five men and
218 two women, four had non-progressive and three had progressive neurological disorders,
219 which is representative of the FES user population (16, 35). The FES systems used by
220 participants varied but all use a single cathode and single anode, and so were classed as
221 'conventional'.

222 *Word count: 126*

223 **Estimate of usage**

224 All participants used ShefStim (Fig. 2) with an average of 1314 heel lifts (steps) per day.
225 There was variability in the number of heel lifts from day-to-day for each participant (for
226 example participant 8) and between participants (participants 5 and 7 versus participant 3).
227 The number of days participants used ShefStim within the two week period also varied, with

228 participants 7 (6/15) and 9 (4/15) using it far less than participants 5 (14/15) or 2 (13/15)
229 (Fig. 2)

230 *Word count: 78*

231

232 **Figure 2:**

233

234 **TS and AS time**

235 TS time for ShefStim took an average of exactly 14 min [range: 12 min 24 s -37 min 30 s]
236 compared to 3 min 20 s [range: 40 s -8 min] for their own FES. The average AS time was 9
237 min [range: 7 min 34 s – 10 min 20 s].

238 *Word count: 51*

239

240 **Diary recording problems during community use**

241 Of the recorded problems 64% [48 problems] were related to setup with poor voice
242 command clarity from the foot sensor and remote control device (e.g. participant 2, day 3
243 “remote voice garbled”), frequent pausing during and/or unacceptable AS specifically cited
244 (e.g. participant 5, day 9 “pausing, why?” and participant 2, day 2 “2x setups as chaplin
245 walk”). 36% [27 problems] were related to external issues, for example participant 8, day 6
246 “despite charging overnight controller battery was flat”. The overall number of reported
247 problems diminished towards the end of the testing period (Fig. 3).

248 *Word count: 94*

249

250 **Figure 3:**

251

252 **User-satisfaction**

253 Overall, on average, participants were as satisfied with ShefStim as with their own FES
254 system (Fig. 4). They were more satisfied with their own FES in terms of: 'Ease of use', which
255 was the criteria most frequently prioritised on QUEST, and 'safety and security'. ShefStim
256 outscored participants' own FES with regards to 'effectiveness', the second most frequently
257 cited priority, and 'ease of adjustment'. On the remaining four criteria the systems scored
258 equally.

259 *Word count: 72*

260 **Figure 4:**

261

262 **Speed**

263 Both FES systems produced the same increase in walking speed [0.06 m/s] compared to no
264 stimulation (Table 3).

265 *Word count: 18*

266

267 **Table 3:**

268

269 **Ankle angles at initial contact**

270 With no stimulation PF with inversion was seen (Table 3). Both ShefStim and conventional
271 systems corrected this; however, ShefStim achieved this to a greater extent (Table 3).

272 *Word count: 27*

273

274 **Foot clearance during swing**

275 This outcome could not be determined for participants 5 and 7 who both exhibited short
276 step lengths and a significant degree of external rotation of the leg during swing, therefore
277 none of the reference points passed the contra-lateral malleolus during swing as was
278 required by the algorithm. The distal toe marker showed the smallest overall clearance
279 values and with ShefStim the clearance was greatest (Table 3). Table 3 shows that without
280 FES, the median value of the medial marker was higher than the lateral; with participant's
281 own FES they were approximately equal and with ShefStim the lateral was higher than the
282 medial. This foot pose at mid-swing was consistent with the ankle angles at initial contact
283 (see above).

284 *Word count: 118*

285 *Total results word count: 584 (excluding sub-headings)*

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287

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DISCUSSION

289 This study sought to investigate the feasibility of unsupervised use of ShefStim by FES users
290 within the community environment. Usage results show ShefStim is a usable device because
291 without exception, albeit with variation, all participants used ShefStim.

292 Previous studies have reported a number of different measures of usage (6, 14, 15, 17, 18).

293 Only our results for steps (heel lifts) per day could be compared to previous, larger, studies

294 (6, 15, 18), with our participants generally walking less. For example Stein *et al's* (6)

295 participants took 1842 (+/- 198) steps per day when first starting to use the Walkaide

296 system and van Swigchem *et al's* (18) took 5733 (SD 2516). Worthy of note was that van

297 Swigchem *et al's* (18) participants were encouraged to wear the NESS L300 for the entire

298 day whereas participants in ours and Stein *et al*'s were not guided in this way. Further, our
299 participants reported a number of problems associated with the pre-commercial nature of
300 the ShefStim system, which may have impacted on use on certain days (see Fig. 3). Further
301 studies should continue to report detailed FES usage to allow further exploration of the
302 population and allow comparison between systems and/or baseline.

303 Results did not fully meet the prediction made by Heller *et al* (1) that ShefStim would result
304 in shorter TS times. There are a number of possible reasons for this. Firstly, Heller used self-
305 report to assess setup time with participants' own FES systems, finding an average of 11
306 minutes. In our study participants were timed during setup in the lab and took an average of
307 3 minutes to setup their own FES systems. In the Heller study participants placed their
308 affected leg in a rigid brace, thereby removing the possibility of significant leg movement. In
309 our study, the participant's leg was not constrained during setup and leg movement
310 detected during the AS process led to pauses which lengthened the process, a problem
311 recorded by participants. Further, our ShefStim users relied on audio feedback from the
312 foot sensor and remote control device, which participants reported was sometimes difficult
313 to hear. Participants also sometimes reached the end of setup and decided that the
314 automatically chosen site was not acceptable, then ran the entire AS again. Although a 'skip-
315 site' function was available (1) to address this issue (alternative sites identified as suitable to
316 be selected manually) participants did not use it, hence further refinement of user training
317 material and/or the user interface is warranted.

318 The finding that, overall, participants were as satisfied with ShefStim as with their own FES
319 systems, is encouraging because unlike conventional foot-drop FES systems ShefStim has
320 not been subject to significant product design. The fact that problems diminished and 'ease

321 of use' was rated lower than participants own FES systems, however, suggests that two
322 weeks was insufficient for participants to fully familiarise themselves with ShefStim.
323 Alternatively it might be due to the cited problems with ShefStim itself. Our results cannot
324 be compared to other studies as QUEST has not been used before in this field of research.
325 Future studies should allow longer unsupervised periods of use and should use a validated
326 measure such as QUEST.

327 Speed increase, for both ShefStim and conventional FES systems, compared to no FES was in
328 keeping with previous studies (21) and classed as clinically meaningful (36). In Heller's study,
329 in which subjects did not have time to accommodate to the automated setup, speed
330 increase (relative to no FES) when using the automated setup system was smaller than with
331 their own system (0.04 m/s vs 0.11m/s). In both studies foot response with AS was
332 improved compared with participants' setup of their own stimulators. Although there is a
333 risk of over-interpretation of the results, our findings may suggest that once users become
334 accustomed to a new FES system, their walking speed is relatively insensitive to small
335 differences in foot response. These findings are supported by the foot clearance results and
336 indicate that the underlying operating principle of an array-based FES system with AS may
337 be more effective at addressing foot-drop than conventional FES systems by reducing
338 human error/influence over electrode placement. However, larger scale study is required to
339 fully substantiate these initial findings.

340 *Word count: 676*

341 **Study limitations**

342 This was a feasibility study with a small sample size, self-referred participants and was not
343 randomised (9, 31). As such, whilst encouraging, results should be viewed with caution. The
344 outcome measures selected would appear appropriate but many have been largely unused
345 in previous research in this field making comparison to previous studies challenging.

346 Further development of the electrode-skin interface is required (12) to negate the need for
347 daily array replacement and improve future commercial viability. Further iterations of
348 ShefStim need to also consider addressing the cited setup and external problems, such as
349 voice command clarity, the impact of pausing on AS time, user training and charging, to
350 facilitate further study and widespread implementation.

351 *Word count: 110*

352

353

CONCLUSION

354 This is the first study of ShefStim and one of very few investigating foot-drop FES both
355 within the lab and during unsupervised use (37, 38). Ultimately this study demonstrates, for
356 the first time, an array-based AS FES system (ShefStim) for foot-drop can be successfully
357 used unsupervised. Despite longer and more problematic setup in the population studied,
358 users were satisfied with it and it would appear to have comparable, if not better, effects on
359 gait than conventional foot-drop FES systems.

360 Further product development and a larger-scale, longer-term study is required before firm
361 conclusions about the efficacy and effectiveness of ShefStim, compared to conventional FES,
362 can be reached.

363 *Word count: 104*

364 *Total word count: 3245*

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366

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484 eng.

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Suppliers

ⁱ Adidas knee support, Adidas, Herzogenaurach, Germany.

ⁱⁱ Odstock Medical Ltd, Salisbury, UK

ⁱⁱⁱ 5x5 PALS[®]Platinum Neurostimulation electrode, Axelgaard Manufacturing co.Ltd, San Diego, USA.

^{iv} Adapted from an I-pod holder, Signalex, Birmingham, UK.

^v Hotter Comfort Concept shoes, Skelmersdale, UK. (for men) and Clarks Un Betty from Unstructured Autumn /Winter 2011 range, Street, UK. (for women)

^{vi} Qualisys, Stockholm, Sweden.

^{vii} C-Motion, Maryland, USA.

^{viii} Matlab[®], Mathworks, Cambridge, UK.

Figure legends

Figure 1: ShefStim system (medial view of leg during AS)

Figure 2: Logged heel lifts (N=7): Blank cells=0 heel lifts; the length of bar represents the number of heel lifts. The median number overall of steps per day was 1314.

Figure 3: Recorded problems over two week unsupervised community use (N=7).

Figure 4: Median QUEST results. Black= own FES system; Grey= ShefStim (n=7). Both systems scored a total of 32 out of 40.

1 **Objective:** To investigate the feasibility of unsupervised community use of an array-based
2 automated setup (AS) functional electrical stimulator (FES) for current foot-drop FES users.

3 **Design:** A feasibility study.

4 **Setting:** Participants' gait, total setup (TS) times and satisfaction were evaluated twice in the
5 gait laboratory. Usage, AS times and problems encountered were recorded during a two
6 week period of unsupervised use.

7 **Participants:** Participants (N=7) with diagnosis of uni-lateral foot-drop of central
8 neurological origin (>6mo), who were regular users of a foot-drop FES system (>3mo).

9 **Intervention:** Array-based AS FES system for foot-drop (ShefStim).

10 **Main Outcome Measures:** Logged usage; TS times for both FES systems and logged AS times
11 for ShefStim; diary recording of problems experienced; Quebec User Evaluation of
12 Satisfaction with assistive Technology (QUEST 2.0) questionnaire; walking speed; ankle
13 angles at initial contact and foot clearance during swing.

14 **Results:** All participants were able to use ShefStim. TS took longer with ShefStim than
15 participants' own FES systems and AS was longer than in a previous study of a similar system
16 (1). Some problems were experienced but overall participants were as satisfied with
17 ShefStim as their own FES systems. The increase in walking speed (N=7), relative to no
18 stimulation, was comparable between both systems and appropriate ankle angles at initial
19 contact (N=7) and foot clearance during swing (N=5) were greater with ShefStim.

20 **Conclusions:** **This study demonstrates, for the first time, that an array-based AS FES system**
21 **(ShefStim) for foot-drop can be successfully used unsupervised.** Despite setup taking longer
22 and some problems users are satisfied with it and it would appear as effective, if not better,
23 at addressing the foot-drop impairment. Further product development of this unique
24 system, followed by a larger-scale and longer-term study is required before firm conclusions
25 about its efficacy can be reached.

26 *Word count: 290*

27 **Key words:** electric stimulation therapy; peroneal nerve; hemiplegia; gait disorders,
28 neurologic; rehabilitation

29 **Abbreviations:**

30 Functional electrical stimulation=FES; Automated setup=AS; Odstock drop foot
31 stimulator=ODFS; Inter-quartile range=IQR; Standard deviation=SD; Total setup=TS; Quebec
32 User Evaluation of Satisfaction with assistive Technology=QUEST; Dorsiflexion=DF;
33 Plantarflexion=PF

34

INTRODUCTION

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The efficacy, and safety, of functional electrical stimulation (FES) as a treatment for foot-drop of central neurological origin is well established (2), however, usability issues have been noted (3, 4). In fact a survey of new and established users of the Odstock drop foot stimulator found that 44% of users reported difficulties in locating the correct electrode position (4), and this finding is of particular relevance to this study. Traditional single-channel surface foot-drop FES systems deliver current via a pair of electrodes, accurate placement of which is crucial to the correct functioning of the system. The optimal site for stimulation may vary from day-to-day and even throughout a day which further complicates the setup process (4). Interestingly, despite wide recognition of this issue (5), only one study specifically reported on the impact of user-defined electrode placement on functional outcomes (1), finding a poorer foot response when participants located electrodes themselves, compared with clinician setup.

In response to this issue, new designs of FES systems have been produced. These include electrodes integrated into cuffs (6, 7) and implantable systems (5, 8). Most recently, Heller *et al.* (1) reported on an array-based FES stimulator for foot-drop. The system uses the principle of a 'virtual electrode'. Stimulation is delivered via a 4x4 cluster of small electrodes, chosen from within an 8x8 array. **The choice of which virtual electrode to use and at what level to stimulate is determined automatically during setup by an algorithm, which uses as its input the foot response to stimulation.** This approach fully automates the setup process (both location and amplitude of stimulation) thus, potentially, reducing setup difficulty. Heller's study found that automated setup (AS) was comparably effective and quicker than user setup conventional FES. **The system, originally studied by Heller, has been**

59 further developed and CE marked as ShefStim. This paper is the first feasibility (9) study of
60 ShefStim which combined a period of unsupervised use in conjunction with gait evaluation
61 at the start and end of the study period. The primary aim was to investigate whether
62 ShefStim could be used, unsupervised, by foot-drop FES users within the community
63 environment. In addition a number of other sub-aims were addressed. These were to
64 investigate:

- 65 1. The community-usage patterns and user-satisfaction with ShefStim.
- 66 2. The total setup (TS) time compared with their own FES system, as well as AS times
67 for ShefStim.
- 68 3. The effects of ShefStim on walking speed, ankle angles (at initial contact) and foot
69 clearance during swing, compared with participants' own FES system.

70 *Word count: 404*

71 **METHODS**

72 **ShefStim system**

73 A detailed description of the operating principles of the stimulator, and changes in order to
74 achieve CE marking, are given in the Heller *et al.* paper (1). The same fixed parameters
75 (monophasic waveform, charge-balanced, 40Hz, 160 μ s) were used but the system used in
76 Heller's study restrained the leg in a support during the AS process. This was deemed
77 impractical for a take-home device so instead users were requested to extend their leg and
78 rest their heel on the floor during home AS.

79 **Figure 1:**

80 The ShefStim consists of (Fig. 1): a leg-worn stimulator (Fig. 1. a.) housed in a modified knee
81 sleeveⁱ (Fig. 1. b.); a flexible printed circuit board array of 64 electrodes (cathode electrodes)
82 (Fig. 1. c.), covered with a thin layer of high resistivity hydrogel (10-12) . Sweat ingress
83 changes the conductive properties of the hydrogel sheet so a replacement array fitted with
84 a new sheet of hydrogel is used each day (12); a conventional footswitchⁱⁱ; a conventional
85 anodeⁱⁱⁱ (Fig. 1.d.) and a foot sensor and remote control device housed in a bespoke foot-
86 pod^{iv} (Fig. 1. e.). **The foot sensor and remote control device** detects foot orientation,
87 provides voice commands during AS and acts **as** a handheld remote unit post AS, allowing
88 the user to pause, and change intensity as required.

89 *Word count: 209*

90 **Donning the system**

91 To don ShefStim the following steps are required:

- 92 1. The footswitch (Fig. 1. f.) is placed under the heel, with the connecting cable
93 extending from the shoe.
- 94 2. The knee sleeve is donned aligning the stimulator pocket with the long axis of the
95 tibia
- 96 3. The stimulator is placed in the knee sleeve's stimulator pocket
- 97 4. The foot-pod, containing the foot sensor and remote control device is positioned
98 over the shoe locating it approximately centrally over the dorsum of the foot and
99 attached with Velcro[®]

- 100 5. Electrode array placement: the centre of the third row of electrodes down from the
101 top of the array is aligned with the head of the fibula and the inner edge parallel to
102 the tibia.
- 103 6. The electrical connector for the array (Fig. 1. g.) is inserted into the array socket on
104 the side of the stimulator and the array is secured with a Velcro® strap.
- 105 7. The self-adhesive anode is positioned over the tibialis anterior.
- 106 8. The footswitch connector (Fig. 1. h.) is inserted in the stimulator.

107 AS is then started.

108 *Word count: 177*

109 **AS**

110 For a more detailed description of the AS algorithm refer to Heller's study (1). The only
111 difference between the algorithm used in Heller's study (1) and the ShefStim algorithm,
112 relates to the cost function used in stage 3 of the setup process. The cost function enables
113 many factors that are not directly comparable (e.g. the angle of dorsiflexion (DF) and the
114 stimulation current) to be combined into one optimisation routine. In this case, for example,
115 the angle of DF and the stimulation current are related and the benefits of increasing DF
116 have to be balanced against the potential disadvantages of increasing current excessively.
117 The cost function attributes each a cost score, the lower the cost the better, and the
118 optimisation routine is used to find a minimum cost solution. Compared with the cost
119 function described in Heller's study, the one used in ShefStim reduced the degree of
120 eversion associated with zero cost from 10 to 5 degrees. This change was implemented
121 following observation of excessive (>10 degrees) eversion in 19% of Heller's participants.

122 *Word Count: 171*

123 **Participants**

124 Ethical Approval was granted from the University of Salford (REP10/113) and the integrated
125 research application system (10/H1003/107) for ten participants. Existing foot-drop FES
126 users within the North-West region were given information by clinicians. Interested
127 participants contacted the chief investigator. Inclusion/exclusion criteria are shown in Table
128 1.

129 **Table 1:**

130 *Word count: 46*

131 **Protocol**

132 At visit 1 participants attended the University of Salford gait laboratory and were provided
133 with standard shoes^v for all conditions to avoid the potential impact of different footwear
134 on foot clearance (13). Participants walked approximately five metres along the gait
135 laboratory up to five times at a self-selected speed initially with no stimulation and then
136 with participant's own FES system (self-setup). Following visit 1 the knee sleeve, stimulator
137 and electrode arrays were prepared for that individual. Participants returned for visit 2
138 where fitting was completed, rising/falling ramps and extension configured, adjustments
139 made to AS settings if required (to ensure appropriate virtual electrode selection) and
140 ShefStim use taught. Following two weeks of unsupervised use of ShefStim at home (with a
141 home-visit after approximately one week to replenish arrays and answer any queries)
142 participants returned to the gait laboratory (visit 3) which duplicated visit 1 but using
143 ShefStim rather than their own FES system.

144 *Word count: 151*

145 **Measures**

146 **Estimate of usage** (between visits 2 and 3)

147 Usage data has been collected in previous foot-drop FES studies (14-18). ShefStim logs the
148 number of heel lifts per day which can be used as an estimate of usage.

149 *Word count: 29*

150 **TS** (visits 1 and 3) and **AS time** (between visits 2 and 3).

151 With one notable exception (1), setup time has been largely neglected in previous foot-drop
152 FES research . TS times, defined as time from first starting to don equipment to being
153 satisfied with the outcome and walking away (including AS time for ShefStim), were
154 recorded for participants' own FES (visit 1) and ShefStim (visit 3). Average AS time (time for
155 AS to complete) was logged by ShefStim.

156 *Word count: 65*

157 **Diary recording problems during community use** (between visits 2 and 3).

158 Problems encountered were recorded in a paper diary by each participant. User-reported
159 problems have been collected previously (15) but never during the period of use. Recorded
160 problems were collated and grouped into two categories (19): External and Setup. External
161 were classed as being independent of the stimulator design and so referred to the housing
162 of ShefStim (knee sleeve), issues with the standard wired footswitch or issues with charging.
163 Setup was defined as any problem related to setup or satisfaction with the foot response.

164 *Word count: 81*

165 **User-satisfaction** (visits 1 and 3)

166 User-satisfaction has previously been captured using purposive questionnaires (4, 15, 18).
167 Given the risk of bias and lack of validation we sought an alternative. The Quebec User
168 Evaluation of Satisfaction with Assistive Technology (QUEST 2.0) device scale (20) is a
169 validated user-satisfaction measure . Participants rated their satisfaction against eight single
170 item criteria (dimensions, weight, ease of adjustment, safety and security, durability, ease of
171 use, comfort, effectiveness) using a five-point Likert scale (1=not satisfied at all to 5= very
172 satisfied: maximum score=40) for their own FES system and ShefStim. In addition,
173 participants ranked their top three priorities from the eight criteria.

174 *Word count: 97*

175 **Speed and ankle angles at initial contact** (visits 1 and 3)

176 Increased walking speed indicates an improvement in overall walking performance (21) and
177 is frequently used in FES research (22, 23). Measuring walking speed over five metres from a
178 static starting position is a **validated measure with neurological populations** (24) and was
179 calculated by averaging the velocity of a recorded waist marker (L3 vertebra) over the
180 measurement space (13).

181 Foot-drop leads to abnormal joint alignment during stance (25) with a tendency for
182 plantarflexion (PF) and inversion (21) which can reduce ankle stability. Sagittal and frontal
183 plane ankle angles were captured at initial contact to measure this. The calibrated
184 anatomical system technique (CAST)(26, 27) was used for shank marker placement. Foot
185 marker placement was based on the shod-foot model by Pratt *et al.* (28).

186 Data for both speed and ankle angles was captured at 100Hz using a 16-camera 3D motion
187 analysis system^{vi}; a fourth-order low-pass Butterworth filter was used with a 6Hz cut-off
188 frequency. Ankle angles at initial contact were analysed using Visual 3D^{vii}

189 *Word count: 152*

190 **Foot clearance during swing** (visits 1 and 3)

191 Foot-drop is associated with an increased risk of tripping and falling due to a lack of foot
192 clearance during swing phase (29). Foot clearance was obtained for seven different points
193 on the shoe sole as described in Thies *et al* (13). Only three of the seven markers from Thies'
194 study (13) (distal toe, medial and lateral forefoot) were investigated since these were
195 deemed most relevant. Healthy gait consistently has a minimum clearance value during
196 swing (13, 30). Hemiplegic gait, however, has an altered clearance trajectory and does not
197 always produce a minimum value during swing, so an alternative and consistently definable
198 point along the trajectory was chosen. Specifically, in this study it was calculated at the
199 moment in time when the reference point on the shoe sole passed the contra-lateral medial
200 malleolus. Data was processed using Matlab^{viii} code (13).

201 *Word count: 133*

202 *Total methods word count: 1311 (not including sub-headings)*

203 **Data Analysis**

204 As a feasibility study (9, 31), statistical analysis was limited to graphical representation of
205 data and descriptive methods. Ratio data (AS log data, speed and ankle angles at initial
206 contact) was analysed using mean and standard deviation (SD). Median was used for

207 skewed data (usage, TS times and toe clearance (32) , with inter-quartile range(IQR)) and
208 ordinal data (QUEST (33)).

209 *Word count: 56*

210 **RESULTS**

211 **Table 2:**

212 Table 2 provides participant characteristics. Prior to data collection three participants were
213 withdrawn (1, 6, 10). The withdrawal of participants 1 and 10 was due to unrelated medical
214 issues. Subject 6 was withdrawn as it became clear, post recruitment, that he was not a
215 regular user of FES for foot-drop. He had discontinued use following ankle instability
216 problems and a number of falls. The average age of the remaining participants was 58 yrs.
217 (SD 12.9) which is comparable to other foot-drop FES studies (1, 21, 34). Of the five men and
218 two women, four had non-progressive and three had progressive neurological disorders,
219 which is representative of the FES user population (16, 35). The FES systems used by
220 participants varied but all use a single cathode and single anode, and so were classed as
221 'conventional'.

222 *Word count: 126*

223 **Estimate of usage**

224 All participants used ShefStim (Fig. 2) with an average of 1314 heel lifts (steps) per day.
225 There was variability in the number of heel lifts from day-to-day for each participant (for
226 example participant 8) and between participants (participants 5 and 7 versus participant 3).
227 The number of days participants used ShefStim within the two week period also varied, with

228 participants 7 (6/15) and 9 (4/15) using it far less than participants 5 (14/15) or 2 (13/15)
229 (Fig. 2)

230 *Word count: 78*

231

232 **Figure 2:**

233

234 **TS and AS time**

235 TS time for ShefStim took an average of exactly 14 min [range: 12 min 24 s -37 min 30 s]
236 compared to 3 min 20 s [range: 40 s -8 min] for their own FES. The average AS time was 9
237 min [range: 7 min 34 s – 10 min 20 s].

238 *Word count: 51*

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240 **Diary recording problems during community use**

241 Of the recorded problems 64% [48 problems] were related to setup with poor voice
242 command clarity from the foot sensor and remote control device (e.g. participant 2, day 3
243 “remote voice garbled”), frequent pausing during and/or unacceptable AS specifically cited
244 (e.g. participant 5, day 9 “pausing, why?” and participant 2, day 2 “2x setups as chaplin
245 walk”). 36% [27 problems] were related to external issues, for example participant 8, day 6
246 “despite charging overnight controller battery was flat”. The overall number of reported
247 problems diminished towards the end of the testing period (Fig. 3).

248 *Word count: 94*

249

250 **Figure 3:**

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252 **User-satisfaction**

253 Overall, on average, participants were as satisfied with ShefStim as with their own FES
254 system (Fig. 4). They were more satisfied with their own FES in terms of: 'Ease of use', which
255 was the criteria most frequently prioritised on QUEST, and 'safety and security'. ShefStim
256 outscored participants' own FES with regards to 'effectiveness', the second most frequently
257 cited priority, and 'ease of adjustment'. On the remaining four criteria the systems scored
258 equally.

259 *Word count: 72*

260 **Figure 4:**

261

262 **Speed**

263 Both FES systems produced the same increase in walking speed [**0.06 m/s**] compared to no
264 stimulation (Table 3).

265 *Word count: 18*

266

267 **Table 3:**

268

269 **Ankle angles at initial contact**

270 With no stimulation PF with inversion was seen (Table 3). Both ShefStim and conventional
271 systems **corrected this; however, ShefStim achieved this to a greater extent** (Table 3).

272 *Word count: 27*

273

274 **Foot clearance during swing**

275 This outcome could not be determined for participants 5 and 7 who both exhibited short
276 step lengths and a significant degree of external rotation of the leg during swing, therefore
277 none of the reference points passed the contra-lateral malleolus during swing as was
278 required by the algorithm. The distal toe marker showed the smallest overall clearance
279 values and with ShefStim the clearance was greatest (Table 3). Table 3 shows that without
280 FES, the median value of the medial marker was higher than the lateral; with participant's
281 own FES they were approximately equal and with ShefStim the lateral was higher than the
282 medial. This foot pose at mid-swing was consistent with the ankle angles at initial contact
283 (see above).

284 *Word count: 118*

285 *Total results word count: 584 (excluding sub-headings)*

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287

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DISCUSSION

289 This study sought to investigate the feasibility of unsupervised use of ShefStim by FES users
290 within the community environment. Usage results show ShefStim is a usable **device because**
291 **without exception, albeit with variation, all participants used ShefStim.**

292 **Previous studies have reported a number of different measures of usage (6, 14, 15, 17, 18).**

293 **Only our results for steps (heel lifts) per day could be compared to previous, larger, studies**

294 **(6, 15, 18), with our participants generally walking less. For example Stein *et al's* (6)**

295 **participants took 1842 (+/- 198) steps per day when first starting to use the Walkaide**

296 **system and van Swigchem *et al's* (18) took 5733 (SD 2516). Worthy of note was that van**

297 **Swigchem *et al's* (18) participants were encouraged to wear the NESS L300 for the entire**

298 day whereas participants in ours and Stein *et al*'s were not guided in this way. Further, our
299 participants reported a number of problems associated with the pre-commercial nature of
300 the ShefStim system, which may have impacted on use on certain days (see Fig. 3). Further
301 studies should continue to report detailed FES usage to allow further exploration of the
302 population and allow comparison between systems and/or baseline.

303 Results did not fully meet the prediction made by Heller *et al* (1) that ShefStim would result
304 in shorter TS times. There are a number of possible reasons for this. Firstly, Heller used self-
305 report to assess setup time with participants' own FES systems, finding an average of 11
306 minutes. In our study participants were timed during setup in the lab and took an average of
307 3 minutes to setup their own FES systems. In the Heller study participants placed their
308 affected leg in a rigid brace, thereby removing the possibility of significant leg movement. In
309 our study, the participant's leg was not constrained during setup and leg movement
310 detected during the AS process led to pauses which lengthened the process, a problem
311 recorded by participants. Further, our ShefStim users relied on audio feedback from the
312 foot sensor and remote control device, which participants reported was sometimes difficult
313 to hear. Participants also sometimes reached the end of setup and decided that the
314 automatically chosen site was not acceptable, then ran the entire AS again. Although a 'skip-
315 site' function was available (1) to address this issue (alternative sites identified as suitable to
316 be selected manually) participants did not use it, hence further refinement of user training
317 material and/or the user interface is warranted.

318 The finding that, overall, participants were as satisfied with ShefStim as with their own FES
319 systems, is encouraging because unlike conventional foot-drop FES systems ShefStim has
320 not been subject to significant product design. The fact that problems diminished and 'ease

321 of use' was rated lower than participants own FES systems, however, suggests that two
322 weeks was insufficient for participants to fully familiarise themselves with ShefStim.
323 Alternatively it might be due to the cited problems with ShefStim itself. Our results cannot
324 be compared to other studies as QUEST has not been used before in this field of research.
325 Future studies should allow longer unsupervised periods of use and should use a validated
326 measure such as QUEST.

327 Speed increase, for both ShefStim and conventional FES systems, compared to no FES was in
328 keeping with previous studies (21) and classed as clinically meaningful (36). In Heller's study,
329 in which subjects did not have time to accommodate to the automated setup, speed
330 increase (relative to no FES) when using the automated setup system was smaller than with
331 their own system (0.04 m/s vs 0.11m/s). In both studies foot response with AS was
332 improved compared with participants' setup of their own stimulators. Although there is a
333 risk of over-interpretation of the results, our findings may suggest that once users become
334 accustomed to a new FES system, their walking speed is relatively insensitive to small
335 differences in foot response. These findings are supported by the foot clearance results and
336 indicate that the underlying operating principle of an array-based FES system with AS may
337 be more effective at addressing foot-drop than conventional FES systems by reducing
338 human error/influence over electrode placement. However, larger scale study is required to
339 fully substantiate these initial findings.

340 *Word count: 676*

341 **Study limitations**

342 This was a feasibility study with a small sample size, self-referred participants and was not
343 randomised (9, 31). As such, whilst encouraging, results should be viewed with caution. The
344 outcome measures selected would appear appropriate but many have been largely unused
345 in previous research in this field making comparison to previous studies challenging.

346 Further development of the electrode-skin interface is required (12) to negate the need for
347 daily array replacement and improve future commercial viability. Further iterations of
348 ShefStim need to also consider addressing the cited setup and external problems, **such as**
349 **voice command clarity, the impact of pausing on AS time, user training and charging,** to
350 facilitate further study and widespread implementation.

351 *Word count: 110*

352

353

CONCLUSION

354 This is the first study of ShefStim and one of very few investigating foot-drop FES both
355 within the lab and during unsupervised use (37, 38). Ultimately this study demonstrates, for
356 the first time, an array-based AS FES system (ShefStim) for foot-drop can be successfully
357 used unsupervised. Despite longer and more problematic setup in the population studied,
358 users were satisfied with it and it would appear to have comparable, if not better, effects on
359 gait than conventional foot-drop FES systems.

360 **Further product development and a larger-scale, longer-term study is required before firm**
361 **conclusions about the efficacy and effectiveness of ShefStim, compared to conventional FES,**
362 **can be reached.**

363 *Word count: 104*

364 *Total word count: 3245*

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366

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Suppliers

-
- ⁱ Adidas knee support, Adidas, Herzogenaurach, Germany.
- ⁱⁱ Odstock Medical Ltd, Salisbury, UK
- ⁱⁱⁱ 5x5 PALS[®]Platinum Neurostimulation electrode, Axelgaard Manufacturing co.Ltd, San Diego, USA.
- ^{iv} Adapted from an I-pod holder, Signalex, Birmingham, UK.
- ^v Hotter Comfort Concept shoes, Skelmersdale, UK. (for men) and Clarks Un Betty from Unstructured Autumn /Winter 2011 range, Street, UK. (for women)
- ^{vi} Qualisys, Stockholm, Sweden.
- ^{vii} C-Motion, Maryland, USA.
- ^{viii} Matlab[®], Mathworks, Cambridge, UK.

Figure legends

Figure 1: ShefStim system (medial view of leg during AS)

Figure 2: Logged heel lifts (N=7): Blank cells=0 heel lifts; the length of bar represents the number of heel lifts. The median number overall of steps per day was 1314.

Figure 3: Recorded problems over two week unsupervised community use (N=7).

Figure 4: Median QUEST results. Black= own FES system; Grey= ShefStim (n=7). Both systems scored a total of 32 out of 40.

Figure 1

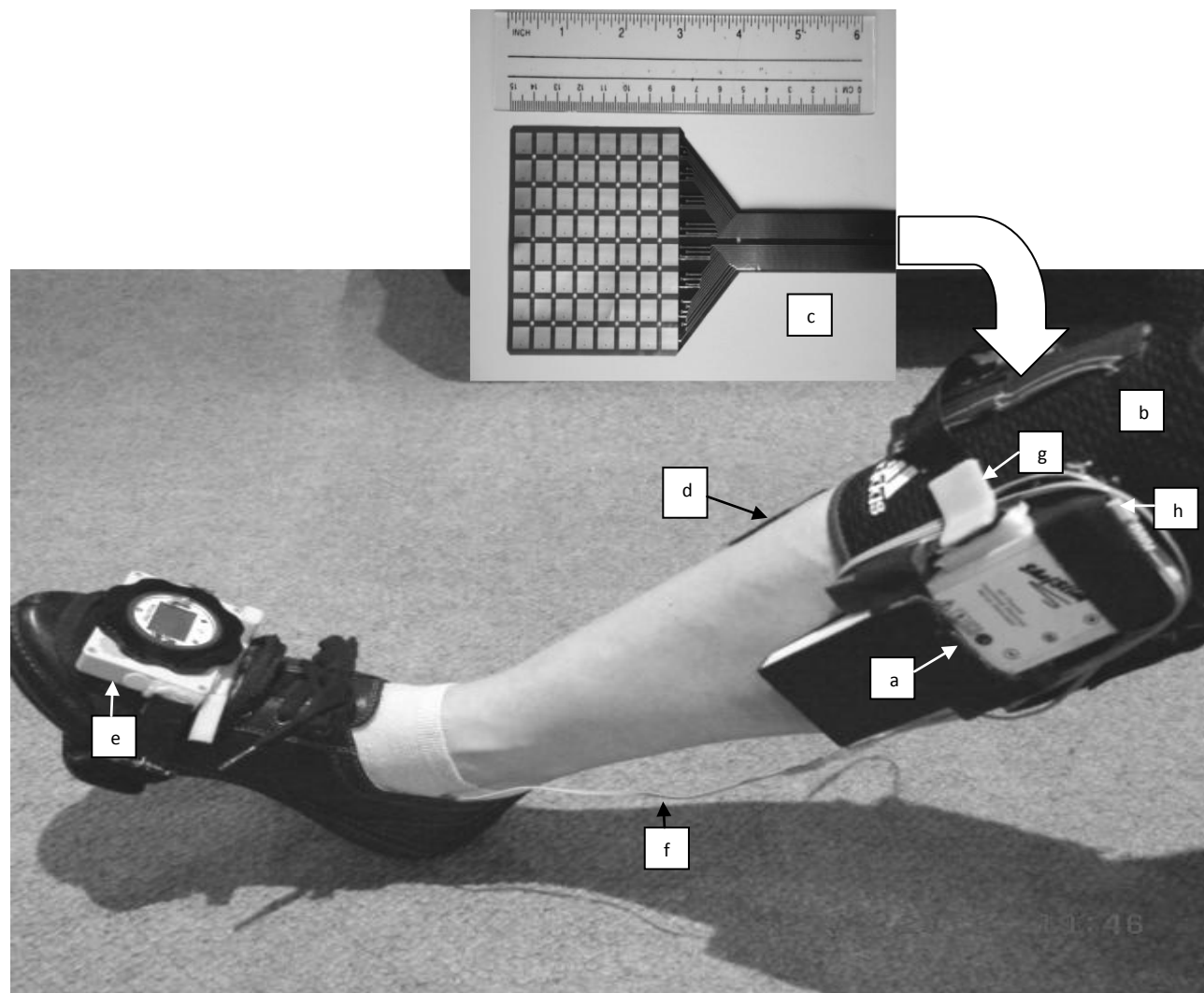


Figure 1: ShefStim (medial view of leg during AS)

Figure 2

		<i>Participant</i>						
		2	3	4	5	7	8	9
<i>Day of Use</i>	1							
	2							
	3							
	4							
	5							
	6							
	7							
	8							
	9							
	10							
	11							
	12							
	13							
	14							
	15							
Total	18841	19879	15016	5844	2058	10992	2209	
Median	1336	2039	1557	389	389.5	1314	276.5	
Range	0-3077	0-2879	0-2628	0-558	0-619	0-3247	0-1593	
IQR	526	693.75	618.75	161.5	277.5	940	582.75	

Figure 2: Logged heel lifts (N=7): Blank cells=0 heel lifts; the length of bar represents the number of heel lifts. The median number overall of steps per day was 1314.

Figure 3

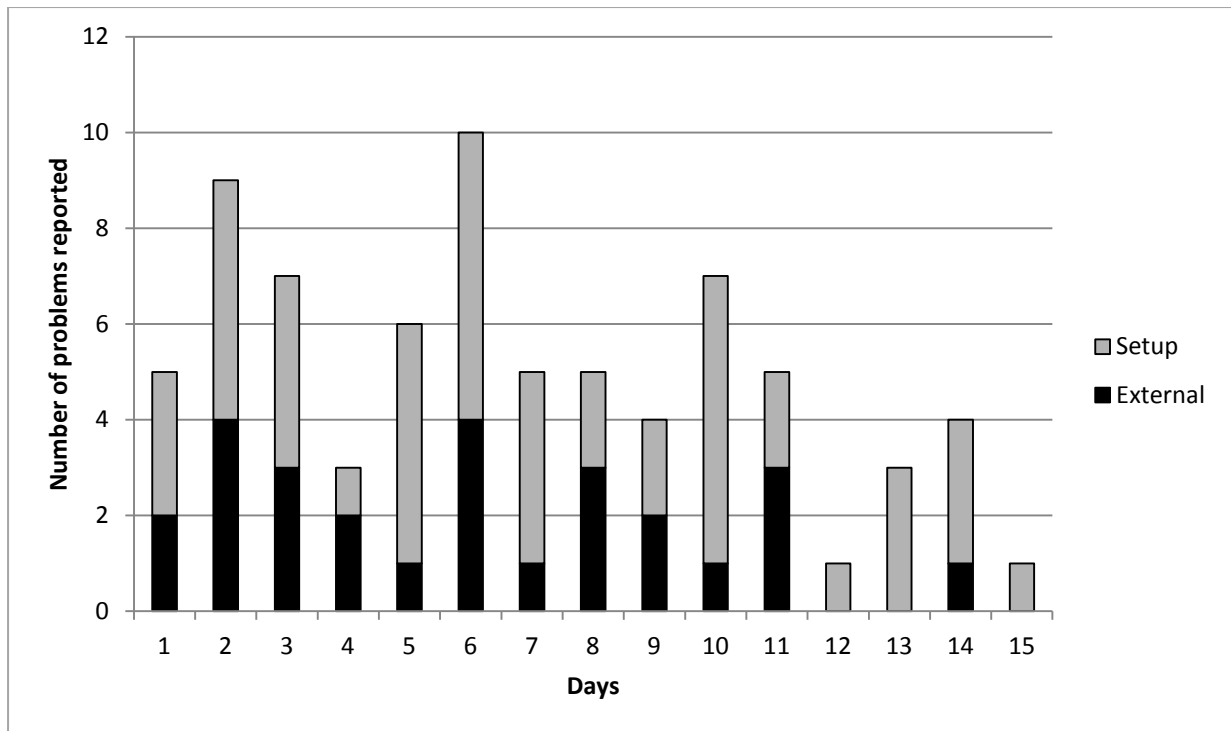


Figure 3: Recorded problems over two week unsupervised community use (N=7).

Figure 4

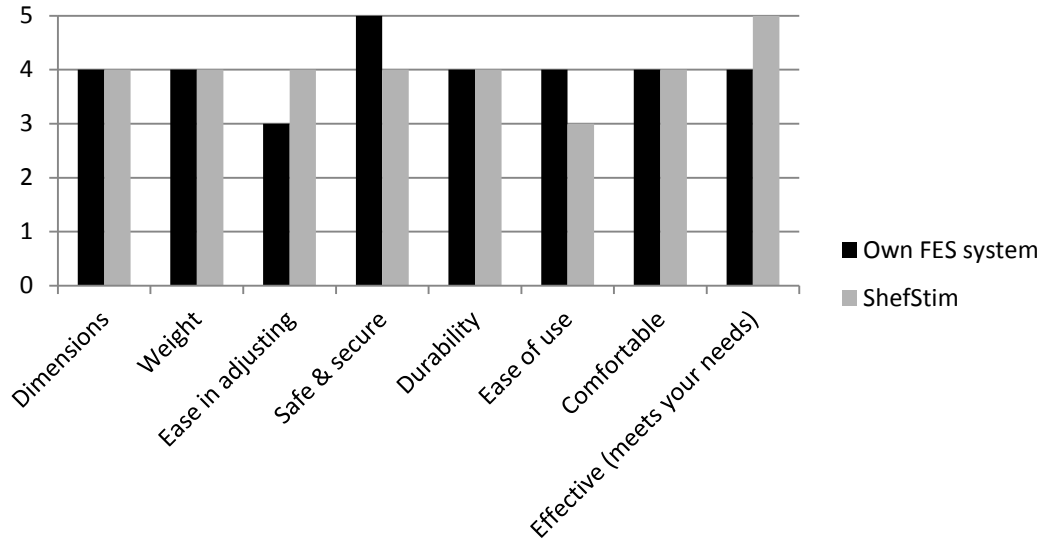


Figure 4: Median QUEST results. Black= own FES system; Grey= ShefStim (n=7). Both systems scored a total of 32 out of 40

Table 1: Inclusion/Exclusion criteria

<u>Inclusion</u>	<u>Exclusion</u>
<ul style="list-style-type: none"> • Unilateral foot-drop caused by disorder of central neurological origin diagnosed at least 6 months prior to the study 	<ul style="list-style-type: none"> • Using alternative method to treat foot-drop (orthosis, physiotherapy, botulinum toxin)
<ul style="list-style-type: none"> • Regular user of a foot-drop FES system, for at least 3 months 	<ul style="list-style-type: none"> • Unable to setup ShefStim, even with assistance
<ul style="list-style-type: none"> • 18 years of age or over 	<ul style="list-style-type: none"> • Contraindications to FES use
	<ul style="list-style-type: none"> • Unable to consent (<25 mini mental state examination)
	<ul style="list-style-type: none"> • Unable to meet protocol/ timetable of study
	<ul style="list-style-type: none"> • Unable to walk 5m without physical assistance

Table 2: Participant demographics. CVA= Cerebro-Vascular Accident/ Stroke; TBI=Traumatic Brain Injury; MS= Multiple Sclerosis; SPWS=Single Point Walking Stick; QBWS= Quad Base Walking Stick

Participant	Age at time of recruitment	Gender	Diagnosis	Side Affected	Assistive device used	Own FES system details
1	58	M	CVA	Right	SPWS	ODFS III® (Odstock Medical Ltd, Salisbury, UK)
2	69	M	CVA	Left	SPWS	ODFS Pace® (Odstock Medical Ltd, Salisbury, UK)
3	58	F	MS	Right	SPWS	WalkAide® (Innovative Neurotronics, Austin, USA)
4	41	M	TBI	Left	None	ODFS Pace® (Odstock Medical Ltd, Salisbury, UK)
5	79	M	CVA	Right	QBWS	ODFS III® (Odstock Medical Ltd, Salisbury, UK)
6	63	M	CVA	Right	SPWS	ODFS Pace® (Odstock Medical Ltd, Salisbury, UK)
7	49	F	MS	Right	SPWS	ODFS Pace® (Odstock Medical Ltd, Salisbury, UK)
8	62	M	CVA	Left	None	ODFS Pace® (Odstock Medical Ltd, Salisbury, UK)
9	51	M	MS	Right	None	ODFS Pace® (Odstock Medical Ltd, Salisbury, UK)
10	26	M	CVA	Left	None	ODFS Pace® (Odstock Medical Ltd, Salisbury, UK)

Table 3: Average speed, ankle angles at initial contact (with SD) and foot clearance during swing (with IQR). =,<,> show the comparison relative to the participant's own FES system.

	No FES	Own FES system	ShefStim
Speed (m/s)	0.72 (0.52)	0.78 (0.51)	0.78 (0.53)=
DF (°)	-3.95 (5.89)	1.96 (5.73)	4.22 (4.64)>
Inv (°)	9.24 (6.12)	1.65 (10.21)	-1.56 (7.73)<
Foot clearance: Distal toe (cm)	1.08 (0.62)	1.58 (0.47)	1.82 (0.89)>
Foot clearance: Medial (cm)	2.71 (1.06)	2.50 (1.12)	2.32 (0.83)<
Foot clearance: Lateral (cm)	1.19 (0.99)	2.38 (0.88)	2.97 (1.82)>