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Integration of Motion Capture into 3D Animation Workflows

Introduction

Motion Capture (MoCap) is a technique for gathering data of the movements of the human body. With the intention of using this information to drive the movements of 3D models in computer-generated animation, MoCap offers significant advantages for producing natural and believable movement in 3D animation and opens up the possibility of bringing to ear acting and live direction to the animation process.

Some major Animation studios expect an output from their animators of around 1-2 seconds of footage per day. So any enhancements to the efficiency of this work are welcomed. At the glance, MoCap technology looks like a brilliant way of automating the labour intensive and very highly skilled process of manually animating 3D characters. However it is wary to think that MoCap can replace animators with robots.

Our group set out to test and evaluate this technology on a live CG animation project and discover how it can actually contribute to the animation production workflow. The project is Called “Icarus” and it is a short animation produced entirely CG. It is a fantastically retelling of the myth of Icarus.

Types of Motion Capture

There are several methods of motion capture.

There are optical methods, such as: Vicon, where white spots are applied to the body at the joints. Their movement across the visual plane of a camera are tracked and analyzed computationally in order to define a motion path for each joint in 3D space. This is widely used in the industry, but has the significant disadvantages of producing noisy data and being limited to movements that take place with the frame of a static camera or set of static cameras.

There are mechanical methods that are attached to the body and measure the rotation of the joints. This is a fairly accurate method of data capture but has the unfortunate effect of influencing the actual movements of the actor who wears it.

The method we used is based on the Xsense motion capture suit which uses inertial sensors attached to the body. This method avoids the major problem of the other methods. It is relatively unnoticeable to the actors movement allowing a large range of movement at both the intimate scale and the large scale up to a radius of 150 metres. The disadvantages are the sensor is fixed and for electromagnetic interference, and absorption. So the data produced is effected by incidental topical noise. Also physical disturbance of the sensors causes errors in the data. e.g. if they are knock out of position in vigorous actions. These problems aside the Motion Capture suit method appears to offer the most flexible system for acquiring natural movement.

The limitations of the MoCap suit are that it records only the limbs and some movements, there is no data for finger movement or facial movement. The Xsense suit does not log any information in the vertical dimension relative to the ground. This must be applied manually afterwards.

In Practice

In practice, we required three people-the actor and a minimum of two people to tend the kit and operate the software. Setting up the suit took time and a certain amount of understanding of how it is supposed to work. The sensors need to be in the right locations and well settled before calibrating the suit.

The MoCap software provided the makers of the suit gives live feedback of the data readings. The data from the sensors is transmitted wirelessly and represented on screen as a standard animation skeleton. Calibration involves the actor taking up predetermined poses and performing controlled predetermined gestures. This allows the software to calculate the relative positions and relative rotations of the sensors. This is further constrained by manually imposing the physical dimensions of the actor. In the first sessions this process took several hours, but with practice we gained an intuition for how the software was calculating and the process could be completed in a few minutes.

The animation process meant that we had to plan the capture session quite carefully. In a process that is quite similar to a simplified film shoot. We produced a list of movements that were needed to tell our story. The scene was set up using improvised props to match the intimate movements dictated by the contents of the story. We also had to be aware of the layout and ground plans of the scene so that the actor’s movements in real space match the architecture of the 3D model set.

The degree of freedom offered by the Xsense MoCap suit allowed a lot of latitude for improvisation in the use of space. E.g. we used the underside of stabilator to simulate the character climbing upside down apillar.

The data gathered of these acting sessions is remarkably sensitive, seeing the representation of the movements on the skeleton reveals how subtle our movements are and how continuous they are even when we are at rest are small rotations of the joints. It is a subtlest of movements that give the unconscious sense of believability that is missing from much computer animation.

The Clean Up

The data in raw form contains errors of various types.

- There are spikes in the motion curves caused by radio frequency interference.
- Erroneous static rotations caused by the sensors slipping out of place after the calibration.
- Fluctuations in the motion paths, caused by signal interference.
- Interpolation errors, caused by inappropriately interpolating data by the MoCap software in intermediary instances of signal failure.

Many of these errors are just a few frames in length and can be fixed quite simply simply deleting data held on the problematic frames and creating an appropriate interpolation between the good data the surrounds it. This is a painstaking and labor intensive process. Longer errors not worthwhile repairing as it is less work to retake the shot or manually animate later on in the process.

The MoCap data is integrated into a control rig which is standard forward kinematic and inverse kinematic rig in Motion Builder software. This means the rotations and translations are applied to the rig. Thus applied, the errors in the data are more easily read and corrected. This is an industry standard animation control rig for driving 3D characters. This rig offers control over most of the body including fingers, jaw axis etc. The MoCap data drives to movement of the parts of the animation rig the it has data for and leaves the rest unchanged. These will be animated manually later.

The animation control rig then has a 3D character model applied to it. The model is moved by the rig and the rig is used in animation software to drive and adjust the final movements of the designed characters.

Conclusion

With a small amount of experience and practice it is possible to produce very good quality motion capture data from the Xsense MoCap sensors.

The product of the Motion Capture data processing is a partially driven character rig, which gives a basic animation that is refined by the animators to fit with the creative intent of the story. This is a significant aid in accelerating the process of 3D CG animation.

It also has the beneficial effect of educating animators about the subtlety of natural movement and how movement convey messages, as the sensitively of the system reveals minute gestures and movements that we do not perceive with the naked eye. Seeing the movements on the skeleton, stripped of the context of the personal data the animator in gaining an objective understanding of how gestures communicate meaning. The team used the MoCap for 23 character animation, but it can be also be used for analysing movement in other contexts e.g. medical analysis of pathological movements caused by injury or deformity. Also for ergonomic simulations of human behaviour.

It is a technology that necessarily cross-disciplinary. Film direction methods and acting techniques are brought to bear and acting techniques are brought to bear and animators must learn how to work with the data. In practice, we required three people— the actor and two people to tend the kit and operate the software. Set calibrating and the process could be completed in a few minutes.

The MoCap data is retargeted onto a control rig which is standard forward kinematic and inverse kinematic rig in Motion Builder software. This means the rotations and translations are applied to the rig. Thus applied, the errors in the data are more easily read and corrected. This is an industry standard animation control rig for driving 3D characters. This rig offers control over most of the body including fingers, jaw axis etc. The MoCap data drives to movement of the parts of the animation rig the it has data for and leaves the rest unchanged. These will be animated manually later.

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